

2.9 Expectation Values

If a system is in state φ which is not an eigen state of a such operator \hat{A} , then it is not possible to say with certainty what measured value will be found for A . Therefore, one has to use the average value $\langle A \rangle = \bar{A}$ which called in Q.M. expectation value of A . however, it is defined mathematically as;

$$\bar{A} = \langle A \rangle = \frac{\int \psi^* \hat{A} \psi d\tau}{\int \psi^* \psi d\tau} \quad \dots\dots\dots(2-17)$$

For a normalized wave function φ ;

$$\bar{A} = \langle A \rangle = \int \psi^* \hat{A} \psi d\tau$$

The probability that a measurement leads to the eigen value for such a case is defined as follows;

$$p_n = \frac{|\int \psi_n^* \phi d\tau|^2}{|\int \phi^* \phi d\tau|} \quad \dots\dots\dots (2-18)$$

For a normalized wave function φ ;

$$p_n = |\int \psi_n^* \phi d\tau|^2$$

Remark: The integration in the last mathematical formula is called overlap integral which is a number, that has a value in the range 0 (lowest value) and 1 (maximum value). For the lowest value, the two functions are exactly different while for the maximum value the functions are exactly similar.

We have learned that for each operator \hat{A} there are a set of eigen values a_n (a_1, a_2, a_3, \dots) with corresponding eigen wave functions ψ_n ($\psi_1, \psi_2, \psi_3, \dots$). The not eigen function ϕ can be expanded in terms ψ_n as follows;

$$\phi = c_1\psi_1 + c_2\psi_2 + c_3\psi_3 + \dots\dots\dots + c_n\psi_n = \sum_n c_n\psi_n \quad \dots\dots\dots(2-19)$$

Equation (2-19) called the completeness or linear superposition principle. Since the total probability is unity we can prove the following important relation $\sum_n |c_n|^2 = 1$,

as follows;

$$\begin{aligned}
 \int_{\text{allspace}} \phi^* \phi d\tau &= 1 \\
 \int \sum_n c_n^* \psi_n^* \cdot \sum_m c_m \psi_m d\tau &= 1 \\
 \sum_n \sum_m c_n^* c_m \int \psi_n^* \psi_m d\tau &= 1 \\
 \sum_n \sum_m c_n^* c_m \delta_{nm} &= 1 \\
 \sum_n c_n^* c_n &= 1 \\
 \sum_n |c_n|^2 &= 1 \quad \dots\dots\dots(2-20)
 \end{aligned}$$

Each term in the last equation ($|c_n|^2$) represent the probability that the system being in state n . Therefore, the physical meaning of this equation is that the total probability (1) is equal to the partial probabilities ($|c_1|^2 + |c_2|^2 + |c_3|^2 + \dots$) for the system to be in all of the different states.

On the other hand, each term may have regarded to the probability that a measurement for an observable A leads to the eigen value a_n , and can be proved as follows;

$$\begin{aligned}
 p_n &= \left| \int \psi_n^* \phi d\tau \right|^2 \\
 &= \left| \int \psi_n^* (c_1 \psi_1 + c_2 \psi_2 + \dots) d\tau \right|^2 \\
 &= \left| c_n \int \psi_n^* \psi_n d\tau \right|^2 \\
 &= |c_n \delta_{nn}|^2 \\
 p_n &= |c_n|^2 \quad \dots\dots\dots(2-21)
 \end{aligned}$$

Actually, we can prove that the probable results on measure the observable A for a system describe by the non-eigen function ϕ , is given by; $\langle A \rangle = \sum_n |c_n|^2 a_n$ as follows;

$$\begin{aligned}
\langle A \rangle &= \int \phi^* \hat{A} \phi \, d\tau \\
&= \int \left\{ \sum_n c_n \psi_n \right\}^* A \left\{ \sum_m c_m \psi_m \right\} d\tau \\
&= \int \sum_n c_n^* \psi_n^* \cdot \sum_m c_m A \psi_m \, d\tau \\
&= \sum_n c_n^* \sum_m c_m a_m \int \psi_n^* \psi_m \, d\tau \\
&= \sum_n \sum_m c_n^* c_m a_m \delta_{nm} \\
&= \sum_n c_n^* c_n a_n \\
\langle A \rangle &= \sum_n |c_n|^2 \cdot a_n \quad \dots\dots\dots (2-22)
\end{aligned}$$

This means that the expectation value of A is the sum of each eigen value a_n times the corresponding partial probability $|c_n|^2$ of the system to be in that state n .

2.11 Variance

The variance defined as the deviation in the measurement result from its expectation value. It is defining by the root-mean-square deviation as follows;

$$\Delta A = \{ \langle (A - \langle A \rangle)^2 \rangle \}^{1/2} \quad \dots\dots\dots (2-23a)$$

The last definition can be formulating to another for as follows;

$$\begin{aligned}
(\Delta A)^2 &= \langle (A - \langle A \rangle)^2 \rangle \\
&= \int \psi^* (A - \langle A \rangle)^2 \psi \, d\tau \\
&= \int \psi^* (A^2 - 2A\langle A \rangle + \langle A \rangle^2) \psi \, d\tau \\
&= \int \psi^* A^2 \psi \, d\tau - \int \psi^* (2A\langle A \rangle) \psi \, d\tau + \int \psi^* \langle A \rangle^2 \psi \, d\tau \\
(\Delta A)^2 &= \langle A^2 \rangle - 2\langle A \rangle \langle A \rangle + \langle A \rangle^2 \\
(\Delta A)^2 &= \langle A^2 \rangle - \langle A \rangle^2 \quad \dots\dots\dots (2-23b)
\end{aligned}$$

H.W: Show that, when a system is describe by an eigen function ψ_n , the probability that a measurement for observable A yields the value a_n is (1). Find the expectation value of A in this case. Calculate the variance in A .

2.12 Equation of motion and constant of motion

When a wave function ψ is an eigen function for the operator \hat{A} with eigen value a . Then all measurements process for the observable A leads to the eigen value a . i.e. $\langle A \rangle = a$. In this case the observable A is called **constant of motion** (or **conserved**), which means that A is time independent quantity. i.e. $\dot{A} = \frac{\partial A}{\partial t} = 0$. Let

us try to prove this fact.

$$\langle A \rangle = \int \psi^* \hat{A} \psi d\tau$$

$$\frac{\partial}{\partial t} \langle A \rangle = \dot{\bar{A}} = \int \left(\frac{\partial \psi^*}{\partial t} \hat{A} \psi + \psi^* \hat{A} \frac{\partial \psi}{\partial t} \right) d\tau \dots\dots\dots (a)$$

$$\left. \begin{aligned} i\hbar \frac{\partial \psi}{\partial t} &= \hat{H} \psi \\ -i\hbar \frac{\partial \psi^*}{\partial t} &= (\hat{H} \psi)^* \end{aligned} \right\} \dots\dots\dots (b)$$

Substitute of equation (b) in equation (a) yields;

$$\dot{\bar{A}} = \int \left\{ \frac{i}{\hbar} (\hat{H} \psi)^* \hat{A} \psi - \frac{i}{\hbar} \psi^* \hat{A} \hat{H} \psi \right\} d\tau$$

According to the definition of Hermitian operator we obtain;

$$\int \hat{A} \psi (\hat{H} \psi)^* d\tau = \int \psi^* \hat{H} \hat{A} \psi d\tau$$

$$\frac{d}{dt} \langle A \rangle = \dot{\bar{A}} = \frac{i}{\hbar} \int \psi^* (\hat{H} \hat{A} - \hat{A} \hat{H}) \psi d\tau$$

In Q.M we define that;

$$\dot{\bar{A}} = \bar{\dot{A}}$$

$$\therefore \bar{\dot{A}} = \frac{i}{\hbar} \int \psi^* (\hat{H} \hat{A} - \hat{A} \hat{H}) \psi d\tau \dots\dots\dots (2-24)$$

$$\hat{\dot{A}} = \frac{i}{\hbar} [\hat{H}, \hat{A}] \dots\dots\dots (2-25)$$

Equation (25) is called the equation of motion, which imply that an observable A is a constant of motion (conserved) when its operator being commute with the Hamiltonian operator.

Example: Show that, the linear momentum p_x of a free particle is a constant of motion.

Solution:

$$\hat{H} = \frac{-\hbar^2}{2m} \frac{\partial^2}{\partial x^2} + V(x)$$

For a free particle $V(x) = 0$, thus;

$$\hat{H} = \frac{-\hbar^2}{2m} \frac{\partial^2}{\partial x^2}$$

$$\bar{p} = \frac{i}{\hbar} [\hat{H}, \hat{p}]$$

$$\bar{p} = \frac{i}{\hbar} (\hat{H}\hat{p} - \hat{p}\hat{H})$$

$$\bar{p}\psi = \frac{i}{\hbar} (\hat{H}\hat{p} - \hat{p}\hat{H})\psi$$

$$\bar{p}\psi = \frac{i}{\hbar} \left\{ \left(\frac{-\hbar^2}{2m} \frac{\partial^2}{\partial x^2} \right) \cdot \left(-i\hbar \frac{\partial \psi}{\partial x} \right) - \left(-i\hbar \frac{\partial}{\partial x} \right) \cdot \left(\frac{-\hbar^2}{2m} \frac{\partial^2 \psi}{\partial x^2} \right) \right\}$$

$$\bar{p}\psi = \frac{i}{\hbar} \left\{ \frac{i\hbar^3}{2m} \frac{\partial^3 \psi}{\partial x^3} - \frac{i\hbar^3}{2m} \frac{\partial^3 \psi}{\partial x^3} \right\}$$

$$\bar{p} = 0$$

Since, $\bar{p} = 0$ thus, $p = \text{constan of motion}$

Example: Prove the Ehrenfest theorems that given by; **a)** $\frac{d}{dt} \langle x \rangle = \frac{1}{m} \langle p_x \rangle$ and **b)**

$$\frac{d}{dt} \langle p_x \rangle = - \left\langle \frac{\partial V}{\partial x} \right\rangle.$$

Proof (a):

$$\langle x \rangle = \int \psi^* \hat{x} \psi dx$$

$$\begin{aligned} \frac{d}{dt} \langle x \rangle &= \frac{d}{dt} \int \psi^* \hat{x} \psi \, dx \\ &= \int x \left(\psi \frac{\partial \psi^*}{\partial t} + \psi^* \frac{\partial \psi}{\partial t} \right) \, d\tau \dots\dots\dots (a) \end{aligned}$$

The T.D.S.E. given by; $i\hbar \frac{\partial \psi}{\partial t} = \frac{-\hbar^2}{2m} \nabla^2 \psi + V(r)\psi$, So, divided by $i\hbar$ yields;

$$\frac{\partial \psi}{\partial t} = \frac{i\hbar}{2m} \nabla^2 \psi + \frac{V(r)\psi}{i\hbar} \dots\dots\dots (b)$$

The complex conjugate of (a) leads to;

$$\frac{\partial \psi^*}{\partial t} = \frac{-i\hbar}{2m} \nabla^2 \psi^* - \frac{V(r)\psi^*}{i\hbar} \dots\dots\dots (c)$$

Substitute of equations (b and c) in (a) yields;

$$\frac{d}{dt} \langle x \rangle = \frac{i\hbar}{2m} \int (\psi^* x \nabla^2 \psi - \psi x \nabla^2 \psi^*) \, d\tau \dots\dots\dots (d)$$

Using Greens Theorem;

$$\int (\psi^* \nabla^2 x \psi - x \psi \nabla^2 \psi^*) \, d\tau = \int (\psi^* \nabla x \psi - x \psi \nabla \psi^*) \cdot ds = 0$$

The boundary condition imposed on ψ make the surface integral equal to zero. Where, the probability of finding the particle outside the volume is equal to zero i.e. the wave function ψ is equal to zero on the surface.

$$\therefore \int (\psi^* \nabla^2 x \psi \, d\tau = \int x \psi \nabla^2 \psi^* \, d\tau$$

Therefore, equation (d) becomes;

$$\frac{d}{dt} \langle x \rangle = \frac{i\hbar}{2m} \int (\psi^* x \nabla^2 \psi - \psi^* \nabla^2 x \psi) \, d\tau \dots\dots\dots (e)$$

Since; $\nabla^2 x \psi = \nabla \cdot \nabla x \psi = x \nabla^2 \psi + \nabla \psi + \nabla \psi$

$$\therefore \nabla^2 x \psi = x \nabla^2 \psi + 2 \frac{\partial}{\partial x} \psi \dots\dots\dots (f)$$

Substitute of equation (f) in (e) we get;

$$\frac{d}{dt} \langle x \rangle = \frac{i\hbar}{2m} \int (\psi^* x \nabla^2 \psi - \psi^* x \nabla^2 \psi - 2\psi^* \frac{\partial \psi}{\partial x}) \, d\tau$$

$$\begin{aligned}
 &= \frac{-i\hbar}{m} \int \psi^* \frac{\partial \psi}{\partial x} d\tau \\
 &= \frac{1}{m} \int \psi^* (-i\hbar \frac{\partial}{\partial x}) \psi d\tau \\
 &= \frac{1}{m} \int \psi^* \hat{p}_x \psi d\tau \\
 \therefore \frac{d}{dt} \langle x \rangle &= \frac{\langle p_x \rangle}{m}
 \end{aligned}$$

Proof (b):

$$\begin{aligned}
 \langle p_x \rangle &= \int \psi^* (-i\hbar \frac{\partial}{\partial x}) \psi d\tau \\
 \frac{d}{dt} \langle p_x \rangle &= -i\hbar \frac{d}{dt} \int \psi^* \frac{\partial \psi}{\partial x} d\tau \\
 \frac{d}{dt} \langle p_x \rangle &= i\hbar \int (\psi^* \frac{\partial}{\partial x} \frac{\partial \psi}{\partial t} + \frac{\partial \psi^*}{\partial t} \frac{\partial \psi}{\partial x}) d\tau \dots\dots\dots (a)
 \end{aligned}$$

Regarding the T.D.S.E.: $i\hbar \frac{\partial \psi}{\partial t} = \frac{-\hbar^2}{2m} \nabla^2 \psi + V(r)\psi$, and dividing by: $i\hbar$ yield;

$$\frac{\partial \psi}{\partial t} = \frac{-\hbar}{2mi} \nabla^2 \psi + \frac{V(r)\psi}{i\hbar} \dots\dots\dots (b)$$

The complex conjugate leads to;

$$\frac{\partial \psi^*}{\partial t} = \frac{\hbar}{2mi} \nabla^2 \psi^* - \frac{V(r)\psi^*}{i\hbar} \dots\dots\dots (c)$$

The substitution of (b) and (c) in (a) leads to;

$$\begin{aligned}
 \frac{d}{dt} \langle p_x \rangle &= -i\hbar \int [\psi^* \frac{\partial}{\partial x} (\frac{-\hbar}{2mi} \nabla^2 \psi + \frac{V}{i\hbar} \psi) + (\frac{\hbar}{2mi} \nabla^2 \psi^* - \frac{V}{i\hbar} \psi^*) \frac{\partial \psi}{\partial x}] d\tau \\
 \frac{d}{dt} \langle p_x \rangle &= \int [\frac{\hbar^2}{2m} \psi^* \nabla^2 \frac{\partial \psi}{\partial x} - \psi^* \frac{\partial}{\partial x} V \psi - \frac{\hbar^2}{2m} \nabla^2 \psi^* \frac{\partial \psi}{\partial x} + V \psi^* \frac{\partial \psi}{\partial x}] d\tau \\
 \frac{d}{dt} \langle p_x \rangle &= -\int (\psi^* \frac{\partial}{\partial x} V \psi - V \psi^* \frac{\partial \psi}{\partial x}) d\tau - \frac{\hbar^2}{2m} \int [\frac{\partial \psi}{\partial x} \nabla^2 \psi^* - \psi^* \nabla^2 (\frac{\partial \psi}{\partial x})] d\tau
 \end{aligned}$$

Apply Greens theorem on the second term we get;

$$\int \left[\frac{\partial \psi}{\partial x} \nabla^2 \psi^* - \psi^* \nabla^2 \frac{\partial \psi}{\partial x} \right] d\tau = \int \left[\frac{\partial \psi}{\partial x} \nabla \psi^* - \psi^* \nabla \frac{\partial \psi}{\partial x} \right] \cdot ds = 0$$

However, the integration of the first term is;

$$= - \int \left(\psi^* \left(V \frac{\partial \psi}{\partial x} + \psi \frac{\partial V}{\partial x} \right) - V \psi^* \frac{\partial \psi}{\partial x} \right) d\tau$$

$$\frac{d}{dt} \langle p_x \rangle = - \int \psi^* \frac{\partial V}{\partial x} \psi d\tau$$

$$\frac{d}{dt} \langle p_x \rangle = - \langle \frac{\partial V}{\partial x} \rangle$$

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