

Lagrange interpolation polynomial

Let, $f(x)$ is a real function defined & continuous on $I=[a,b]$, and assume that we have the following data base

$$y_i = f(x_i) , i=1,2,\dots,n$$

X	x_0	x_1	x_2	x_n
Y	y_0	y_1	y_2	y_n

where $\{X_i\}_{i=0}^n \in I$.

Our aim is to find the polynomial $P_n(x)$, which satisfies the **interpolation condition**

$$f(x_i) = P_n(x_i)_{i=0}^n.$$

It has been proved that, there exists only one polynomial of order less than or equal n , such that the **interpolation condition** is satisfied. **Lagrange** showed that this polynomial can be written as follows:

$$P_n(x) = \sum_{k=0}^n f(x_k)L_k(x),$$

$$L_k(x) = \prod_{\substack{i=0 \\ i \neq k}}^n \frac{(x - x_i)}{(x_k - x_i)} \quad k = 0,1,2 \dots n$$

Which is called the **Lagrange interpolation formula**

Theorem:- $f(x) = P_n(x) + T(x)$,

where $T(x)$ is the truncation error formula, which takes the form

$$T(x) = \frac{f^{(n+1)}(\delta(x))}{(n+1)!} \prod_{i=0}^n (x - x_i), \quad \delta \text{ is a number depends on } x$$

Remark:- from last theorem, if f is a polynomial of degree less than or equal n , then $T(x) = 0$, which means $f(x) = P_n(x), \forall x \in [a, b]$.

Steps of Lagrange algorithm

1-input the vectors $X = X_i)_{i=0}^n, Y = Y_i)_{i=0}^n$

2-input x^*

3-find the approximate value of $f(x^*)$, using **Lagrange formula**

$$f(x^*) \cong P_n(x^*) = \sum_{k=0}^n f(x_k)L_k(x^*)$$

Example:- Let f is a continuous function, find $f(4.5)$, from the following data base, by using Lagrange algorithm

x	2	4	5
y	3	15	24

Solution

Firstly, we write the general form of Lagrange formula

$$\begin{aligned}
 p_2(x) &= \sum_{k=0}^2 f(x_k) L_k(x) = f(x_0)L_0(x) + f(x_1)L_1(x) + f(x_2)L_2(x) \\
 &= \frac{(x-x_1)(x-x_2)}{(x_0-x_1)(x_0-x_2)} f(x_0) + \frac{(x-x_0)(x-x_2)}{(x_1-x_0)(x_1-x_2)} f(x_1) + \frac{(x-x_0)(x-x_1)}{(x_2-x_0)(x_2-x_1)} f(x_2) \\
 p_2(2) &= \frac{(4.5-4)(4.5-5)}{(2-4)(2-5)} 3 + \frac{(4.5-2)(4.5-5)}{(4-2)(4-5)} 15 + \frac{(4.5-2)(4.5-4)}{(5-2)(5-4)} 24 = \frac{77}{4} \\
 &= 19.25
 \end{aligned}$$

Note that, we can get more accurate results if we increase the dimension of the data base.

Inverse Interpolation

Assume that $f(x^*)$ is known, where f is a continuous $x^* \neq x_i)_{i=0}^n$, $x^* \in [x_0, x_n]$ function. If we would like to find the value of x^* , this operation is called, the inverse interpolation.

In order to find a solution for this problem, we can use the Lagrange algorithm, with switch places of x and y .

i.e., we consider y is the independent variable and x is the dependent variable. Therefore, the inverse Lagrange formula takes the form

$$x^* = p_n(y) = \sum_{k=0}^n x_k L_k(y)$$

$$L_k(y) = \prod_{\substack{i=0 \\ i \neq k}}^n \frac{(y - y_i)}{(y_k - y_i)}$$

Example:- Find the value of x^* such that $f(x) = 0$ (the root of f), from the following data base, by using Inverse Lagrange formula.

x	0	2	5
y	-1	3	24

$$p_2(x) = \sum_{k=0}^2 f(x_k) L_k(x) = f(x_0)L_0(x) + f(x_1)L_1(x) + f(x_2)L_2(x)$$

$$x = \frac{(y-y_1)(y-y_2)}{(y_0-y_1)(y_0-y_2)}x_0 + \frac{(y-y_0)(y-y_2)}{(y_1-y_0)(y_1-y_2)}x_1 + \frac{(y-y_0)(y-y_1)}{(y_2-y_0)(y_2-y_1)}x_2$$

$$x^* = \frac{(0-3)(0-24)}{(-1-3)(-1-24)}(0) + \frac{(0-(-1))(0-24)}{(3-(-1))(3-24)}(2) + \frac{(0-(-1))(0-3)}{(24-(-1))(24-3)}(5)$$

$$x^* = 1$$

Remarks

1-in the last example, it is clear from the data base that the root of f belongs to (0,2), and that because the sign of $f(0)$ is negative and the sign of $f(2)$ is positive .

2-from the last example we conclude that, we can find the approximate root of $f(x) = 0$, when the form of the function f is unknown, and we only have the values of f at some points.