Chapter 5

Numerical integration

In this chapter, we study some methods; used to find the approximate value for the definite following integral

$$\int_{a}^{b} f(x)dx \qquad (\forall x \in [a,b] f \in C[a,b]),$$

when it's difficult to find the exact value by using known methods (integration methods), such as:

$$\int_a^b e^{x^2} dx$$

The general idea of the integration methods is to divide the interval [a, b], into n of subintervals :

 $[a,b] = [x_0, x_1] \cup [x_1, x_2] \dots \cup [x_{n-1}, x_n].$

It is not needed to be the distances between the points $\{x_i\}$ are equal.

Next, we consider the polynomial $p_n(x)$ as an approximate form for f.

$$f(x) \cong p_n(x), \ \forall x \in [a, b]$$

which means the problem becomes

$$\int_{a}^{b} f(x) dx \cong \int_{a}^{b} p_{n}(x) dx$$

From the last form, we note that, the formula of numerical integration depends on the way of choosing the polynomial p_n .

The general formula of integration methods takes the form:

$$\int_{a}^{b} f(x)dx \cong \int_{a}^{b} p_n(x) dx = \sum_{i=0}^{n} a_i f(xi) \dots \dots (*)$$

where,

 $\{a_i\}_{i=0}^n$ are called the coefficients

 $\{x_i\}_{i=0}^n$ are called the nodes.

If we used Lagrange polynomial, we could very easy get $\{a_i\}_{i=0}^n$, $\{x_i\}_{i=0}^n$ as follows:

We divide the interval [a, b], to the n of subintervals

 $[a,b] = [x_0, x_1] \cup [x_1, x_2] \dots \cup [x_{n-1}, x_n],$

where the distances between the nodes $\{x_i\}_{i=0}^n$ are equal

i.e. $x_{i+1} - x_i = h$

Thus $f(x) = p_n(x) + T(x)$, $\forall x \in [a, b]$,

where p_n is the Lagrange polynomial

$$\int_{a}^{b} f(x)dx = \int_{x_{0}}^{x_{n}} p_{n}(x) dx = \int_{x_{0}}^{x_{n}} \sum_{i=0}^{n} L_{i}(x)f(x_{i})dx + \int_{x_{0}}^{x_{n}} \frac{f^{(n+1)}(\delta(x))}{(n+1)!} \prod_{i=0}^{n} (x-x_{i})dx,$$

where $\int_{x_0}^{x_n} \frac{f^{(n+1)}(\delta(x))}{(n+1)!} \prod_{i=0}^n (x-x_i) dx$, is the truncation error formula

So,
$$\int_{a}^{b} f(x) dx \cong \sum_{i=0}^{n} (\int_{x_{0}}^{x_{n}} L_{i}(x) dx) f(x_{i})) \dots (1)$$

which means

$$a_i = (\int_{x_0}^{x_n} L_i(x) dx)$$

In the last formula,

For n=1, method is called (**Trapezoidal method**),

For n=2, method is called (**Simpson method**).