Examples on Mamdani FIS system

Ex1: Design a fuzzy lighting controller system, in which the control system dim the bulb light automatically according to the environmental Light. Assume that the inputs to the system are the environmental light x1 and the changing rate of the environmental light x2. While the output variable which represents the control value to the dimmer is DM. Consider the following assumption:

Assume that x1 can be *Dark* (*D*), *Medium* (*M*), and *Light* (*L*) and its range between <u>120 and 220</u>, with three membership functions: L(130,150), (130, 150 190,210), and $\Gamma(190, 210)$ for *D*, *M*, and *L* respectively.

x2 ranges between <u>-10 and +10</u> and is divided into *Negative-Small* (*NS*), *Zero* (*ZE*), and *Positive-Small* (*PS*), with three membership functions: (-20, -10, 0), (-10, 0, 10), and (0,10,20) for *NS*, *ZE*, and *PS* respectively.

The output *DM* ranges between <u>0 and 10</u> and is divided into *Verysmall* (*VS*), *Small* (*S*), *Big*(*B*), and *Very-big* (*VB*), with four membership functions: L(2,4), (2,4,6), (4,6,8), and $\Gamma(6,8)$ for *VS*, *S*, *B*, and *VB* respectively.

Evaluate the output for x1 = 125 and x2 = -6, having the following fuzzy rule base:

x1	D	Μ	L
x2 >>			
PS	В	S	VS
ZE	В	В	S
NS	VB	В	В

Solution:





X1=125 then it is D X2= -6 then it is ZE and NS Therefore two rules will be fired: IF X1 IS D AND X2 IS ZE THEN DM IS B IF X1 IS D AND X2 IS PS THEN DM IS VB

For the first rule	$\mu_{X1} = 1$ and $\mu_{X2} = 0.4$	thus, $\mu_{DM} = 0.4$
For the second rule	$\mu_{X1} = 1$ and $\mu_{X2} = 0.6$	thus, $\mu_{DM} = 0.6$
XT .1 .1 .1		

Now, the control action will be:

 $dm = \{0, 0, 0, 0, .4, .4, .5, .6, .6, .6\}$

Finally, we apply center of gravity (CoG) defuzzification in order to obtain final crisp output:

$$DM = \frac{(0*0) + (0*1) + \dots + (0*4) + (.4*5) + (.4*6) + (.5*7) + (.6*8) + \dots + (.6*10)}{0+0+\dots+.4+.4+.5+.6+.6+.6} = \frac{24.1}{3.1} = 7.77$$

Ex2: Consider a fuzzy logic controller with two inputs x, y and a single output u, in which each of the inputs/output variables is quantified into three fuzzy sets with membership functions as illustrated in the table bellow. Suppose that the range of each variable is [0, 10] with number of intervals = 10.

	Х	Y		U	
Fuzzy	Membership	Fuzzy	Membership	Fuzzy	Membership
terms	function	terms	function	terms	function
Ν	L(x; 2,5)	Ν	L(y;2,4)	S	L(u;0,3)
Z	(x;2,5,8)	Z	(y;2,4 ,6, 8)	Μ	(u;2,5,8)
Р	Γ(x;6,8)	Р	Г(у;6,8)	Н	Γ(u;6,8)

Find the control action if x=3 and y=5, knowing that the fuzzy rules are

^	N	Ζ	Р
Ν	S	М	М
Ζ	Μ	Н	Η
Р	Μ	Н	Н

Solution:



1. If (X is N) and (Y is Z) then (U is M) $\rightarrow \sim_{N}(x) = .66; \sim_{Z}(y) = 1 \rightarrow; \sim_{M}(u) = 0.66$



2. If (X is Z) and (Y is Z) then (U is H) $\rightarrow \sim_Z(x) = .33; \sim_Z(y) = 1 \rightarrow; \sim_M(u) = 0.66$

 $u = (0 + 0.333*3 + 0.666*(4 + 5 + 6) + 0.333*(7 + 8 + 9 + 10))/(0.333*5 + 0.666*3) \approx 6$

Ex3: Consider a fuzzy logic controller is used to control the speed of a motor by changing its input voltage (V) according to two input variables; speed (SP), and speed change rate SC. Let the fuzzy set of SP be {*Slow* (*S*), *Normal* (*N*), *Fast* (*F*)}, and the fuzzy set for SC be {*Low* (*L*), *Medium* (*M*), *High* (*H*)}, and for the control action be {*Slow Down* (*DN*), *No Change* (*NC*), *Speed Up* (*Up*)}, where, (SP \in [500, 1000]), (SC \in [0, 10]), and (V \in [2, 3]) with step = 0.1. The membership functions for the input/output variables are described in table 1. Find the control action if SP=910 And SC= 6.5 based on the fuzzy rules shown in table 2.

Table 1					
	SP	SC		V	
Term	MF	Term	MF	Term	MF
S	L(600,750)	L	L(2,4)	DN	L(2.2 ,2.5)
NI	Λ(600,750,900)	Μ	(2,4,6,	NC	Λ(2.4,
IN			8)		2.5,2.6)
Б	Г(750,900)	Н	Γ(6,8)	Up	Γ(2.5,
Г					2.8)

Table 2			
^	S	Ν	F
L	Up	NC	NC
Μ	Up	NC	NC
Η	NC	DN	DN



 $V = \begin{bmatrix} 0.25 * (2.1 + 2.2 + 2.3 + 2.4) + 0.75 * 2.5 \end{bmatrix} / \begin{bmatrix} 0.25 * 4 + 0.75 \end{bmatrix} = 4.125 / 1.75 = 2.357$