

Yield Line Analysis of Slabs

A method of slab analysis, which permits the determination of failure moments in slabs of irregular as well as rectangular shapes for a variety of support conditions and loading.

1-For the Hinged Slab

As load increase, $M_{max} \rightarrow M_{ult}$.

→ Tension steel yields along line of M_{max}

→ Curvature increase sharply,

→ Deflection increase sharply,

→ "Plastic Deformation",

→ a "Hinge" form at "Yield Line",

→ "Plastic Hinge",

At plastic hinge, $M_p = M_n$,

A "Mechanism" forms (segment of the slab move),

→ Failure (Collapse).

Note

$$M_n = \rho \cdot b \cdot d^2 \cdot f_y \left(1 - 0.59 \rho \frac{f_y}{f_c'}\right)$$

2-For the Fixed Slab (Intermediate)

As load increase, M_{max}^- and $M_{max}^+ \rightarrow M_{ult}$.

→ Tension steel yields at critical sections,

→ Rotation occurs,

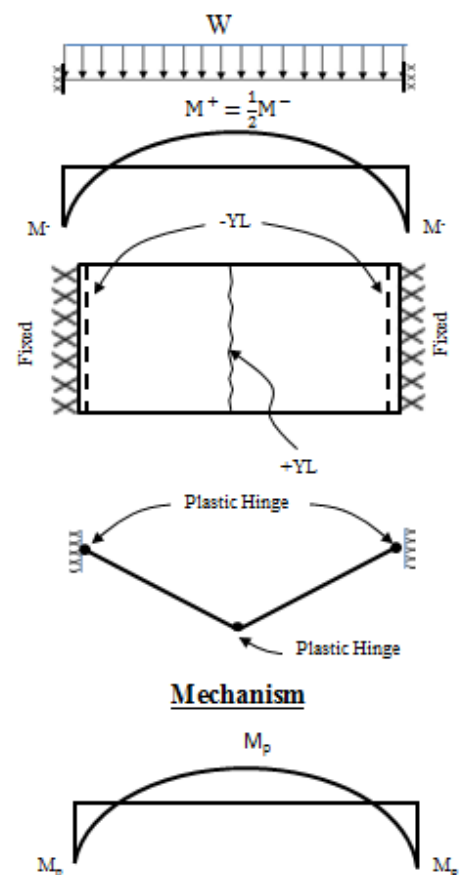
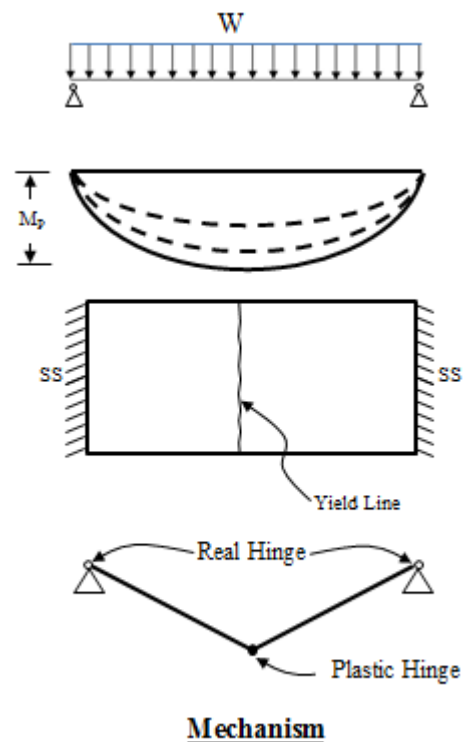
→ At supports $M^- = M_p$ then "Two Plastic Hinge" forms,

→ At mid span $M^+ = M_p$ a third "Plastic Hinge" forms,

→ A "Mechanism" forms (segment of the slab move),

→ Unstable,

→ Failure (Collapse).



Mechanism: the segment of the slab between the hinge and the supports are able to move without an increase in load (collapse).

Location of Yield Line

Yield Line location and orientation is evident in simple and fixed slab. For the other cases, the axis of rotation will be located along the lines of supports or over point supports (columns). The slab segments rotate as rigid bodies about these axes of rotation.


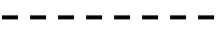

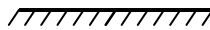

+YL= Associated with tension at BOTTOM of slab.

-YL= Associated with tension at TOP of slab.

Guide lines for drawing axes of rotation and yield lines

- 1- Yield lines are straight.
- 2- Axes of rotation lie along lines of support (the support line may be a real hinge or it may establish the location of a yield line which acts as a plastic hinge).
- 3- Axes of rotation pass over columns (supports).
- 4- A yield line (or its extend) passes through the intersection of the axes of rotation of adjacent slab segments.

Notion

	Positive Yield Line
	Negative Yield Line
	Fixed Support
	Simple Support
	Free Edge

Method of Analysis

There are two methods of analysis according to Yield Line:-

- 1- Virtual work method (Mechanism method).
- 2- Equilibrium method (Statical method).

Isotropically Reinforced Slab

The resisting moment is the same along any line regardless of its location.

Orthogonally Anisotropic (or orthotropic) Reinforced Slab

The resisting moments are different in two perpendicular directions.

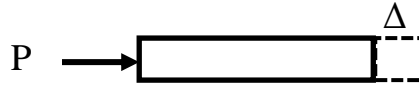
Yield Line Analysis by the Virtual work method

There are two types of Virtual work:-

1-Translational Virtual work

In this case, the displacement (Δ) shall be in the same direction of force (P) and the work done is:-

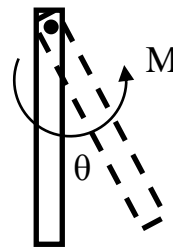
$$\text{Work done} = P \times \Delta$$



2-Rotational Virtual work

In this case, the rotation (θ) shall be in the same direction of moment (M) and the work done is:-

$$\text{Work done} = M \times \theta$$



The external work done by the loads to cause a small Virtual deflection= The internal work done by the slab as rotates at the Yield Line. Thus, a relation between the loads and the ultimate resisting moments of the slab is obtained.

$$\text{External work } (W_E) = \text{Internal work } (W_I)$$

External work (W_E) = Load x Displacement (Deflection)

→ For concentrated load, (W_E) = $P \times \delta$

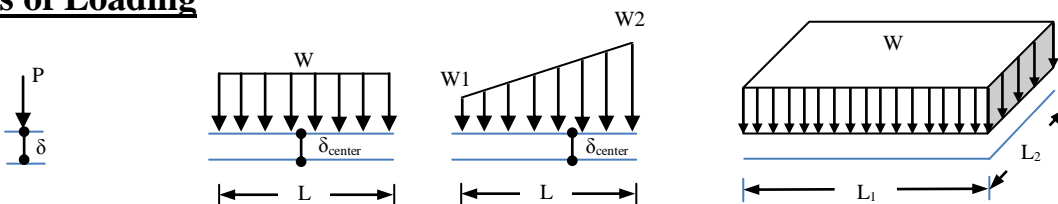
→ For line load, (W_E) = $W \times L \times \delta_{\text{center}}$

→ For uniformly distributed load, (W_E) = $W \times \text{Area} \times \delta_{\text{center}}$

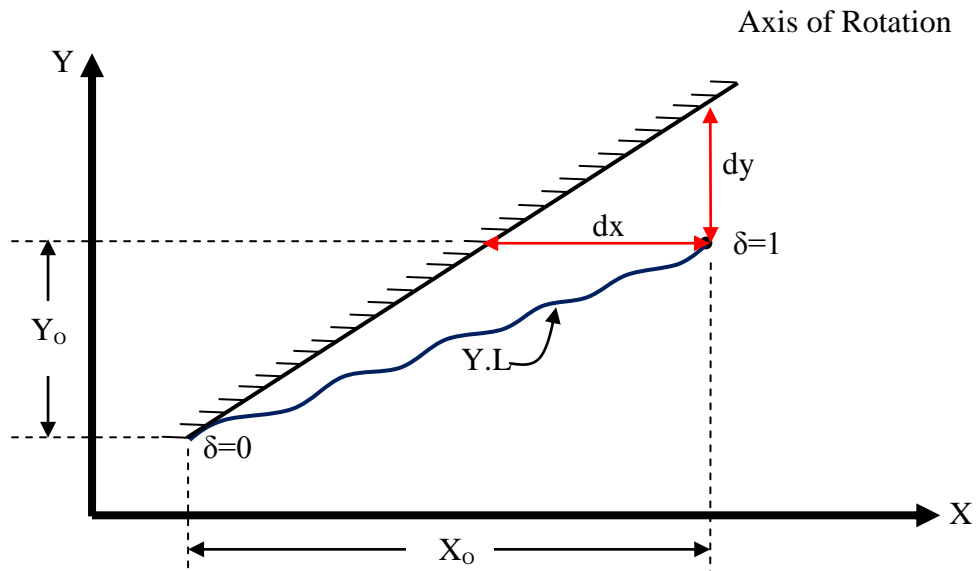
Internal work (W_I) = Moment x Rotation

$$= m \times L \times \theta$$

Types of Loading



Rotation about Inclined Axis



Y_o =Projection of Yield Line on Y-Axis.

X_o =Projection of Yield Line on X-Axis.

dy =Vertical distance measured from (δ) to Axis of Rotation.

dx =Horizontal distance measured from (δ) to Axis of Rotation.

δ =Deflection at any point lie along Yield Line.

$$\text{Internal work } (W_I) = m * L_x * \theta_x + m * L_y * \theta_y = m * X_o * \frac{\delta}{dy} + m * Y_o * \frac{\delta}{dx}$$