

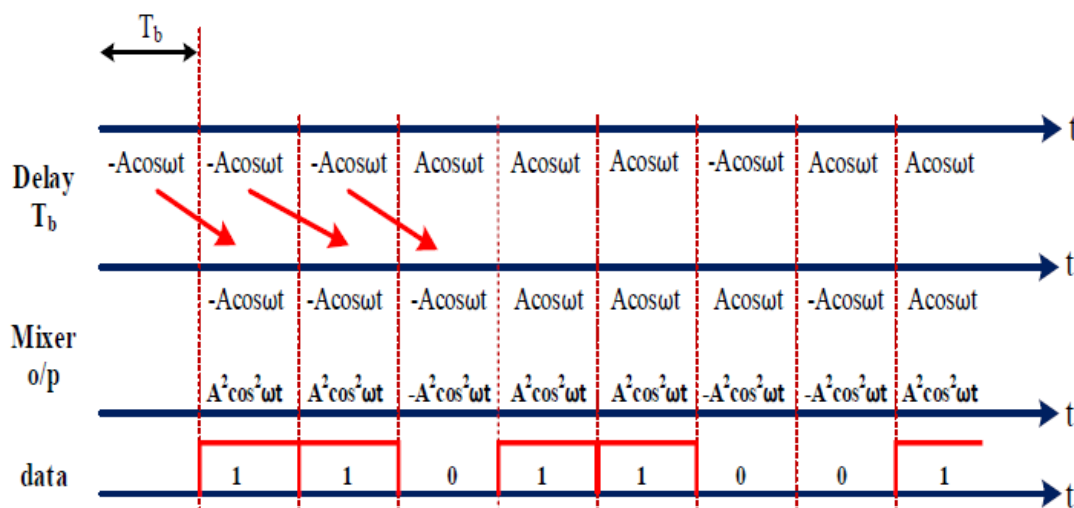
The extra requirement for DPSK noncoherent detection is the analogue delay line of  $T_b$ . The DPSK is delayed by  $T_b$  and then multiplied with itself, LPF then a threshold comparator.

### Ex 6-15:

With the help of data of previous example, explain the operation of DPSK detector.

### Solution:

$-A \cos \omega t$  &  $+A \cos \omega t$  will be used for  $180^\circ$  &  $0^\circ$  phase shift then;



### H.W:

Repeat encoder and decoder operations when  $x(0)=0$ , and comment to the results.

**Advantages of DPSK:**

- 1- Noncoherent detection (no carrier generation)
- 2- No phase ambiguity (possible data complement) since the decoded data is independent of random initial choice of the state of D-FF ( $x(0)$ ).

**Disadvantages of DPSK:**


The only disadvantage is the need of analogue delay line by  $T_b$  time. This is usually implemented using charge coupled devices (CCD) as analogue delay line.

### Multilevel keying Technique (M-ary Signalling):

These are usually used for bandwidth economical systems (such as telephone channels) to increase data rate transmission over bandlimited channels.

#### Concept:

The concept of M-ary signaling is to group binary bits and deal with them as symbols. Hence, M is taken as  $2^r$  (2,4,8,16,...). For example M=4 means  $r=2$ .

data 1 0 0 1 1 1 0 0 0 1 1 1 1 0  


grouping of 2-bits ( $r=2$ ,  $M=4$ ) i.e. 4 level

Then each successive 2-bits has grouped and considered as symbol. Hence, these will be four possible signals  $\phi_0(t)$ ,  $\phi_1(t)$ ,  $\phi_2(t)$  and  $\phi_3(t)$  for the possible groups of “00”, “01”, “10” and “11”. And so on for  $M=8$ ,  $r=3$ , ...

In general:

$$r = \log_2 M$$

bits/symbol

... (6-30)

$$M = 2^r$$

no. of channel states

... (6-31)

$$T_s = \frac{1}{R_s} = (\log_2 M) \cdot T_b$$

symbol duration

... (6-32)

$$R_s = \frac{R_b}{\log_2 M}$$

symbol rate (baud rate)

... (6-33)

### M-ary ASK (MASK):

M carrier level are used for M=4 then:

$$\phi_0(t) = 0$$

$$\phi_1(t) = A \cos \omega_c t$$

$$\phi_2(t) = 2A \cos \omega_c t$$

$$\phi_3(t) = 3A \cos \omega_c t$$

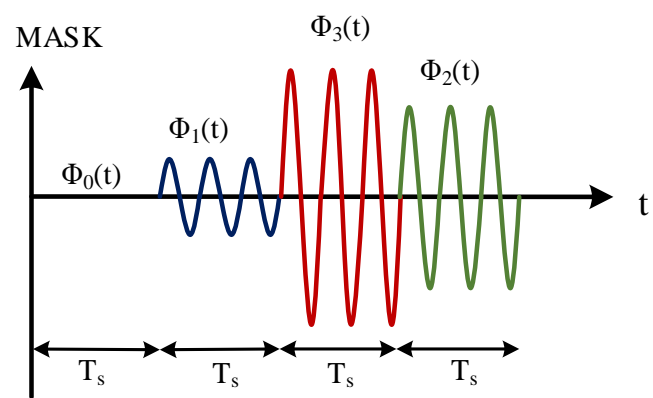
... (6-34)

For data

0 0 0 1 1 1 1 0

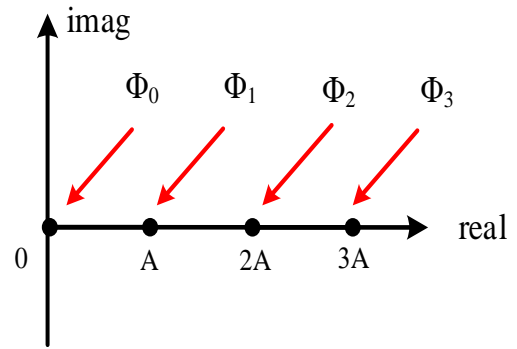
$\phi_0$     $\phi_1$     $\phi_3$     $\phi_2$

Then transmitted waveforms will be:  $\phi_0(t)$ ,  $\phi_1(t)$ ,  $\phi_3(t)$ ,  $\phi_2(t)$  with symbol duration  $T_s = 2T_b$



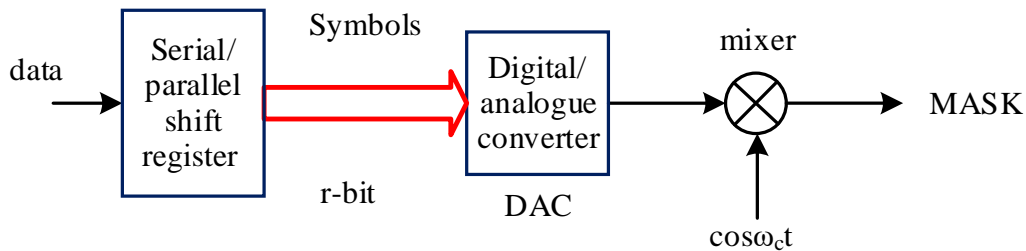
### Signal State Diagram

This is a representation of carrier signals in complex plane (x-axis  $\equiv$  real part  $\equiv \cos \omega_c t$ ) & (y-axis  $\equiv$  imaginary part  $\equiv \sin \omega_c t$ ) of  $e^{j\omega_c t}$ .

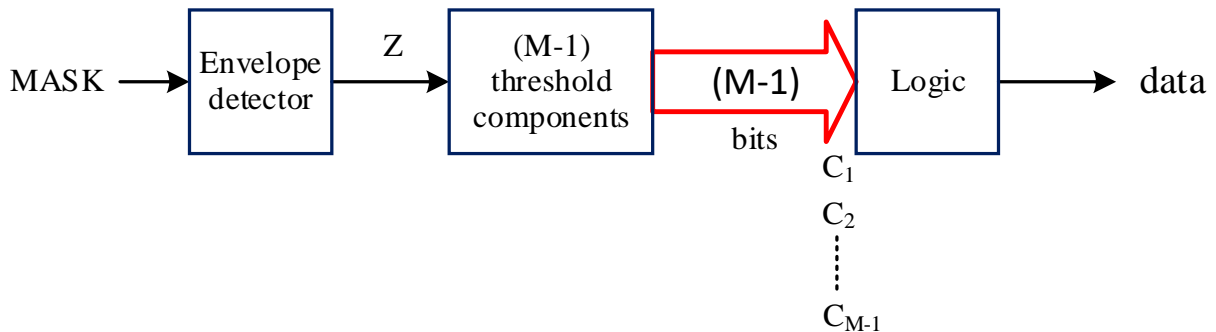


To draw the signal state diagram of 4 level MASK then on the real axis  $\Phi_0, \Phi_1, \Phi_2$  &  $\Phi_3$  will be found since modulation is done in amplitude of the inphase component ( $\cos \omega_c t$ ) of the carrier.

### Simple MASK modulator:



### Simple MASK demodulator (noncoherent):



For  $M=4$  then 3 comparators with  $V_{th} = \left(\frac{A}{2}\right), \left(\frac{3A}{2}\right) \& \left(\frac{5A}{2}\right)$  are used and logic truth table will be:

$C_1$	$C_2$	$C_3$	data
0	0	0	00
1	0	0	01
1	1	0	10
1	1	1	11

$C_1, C_2, C_3$  are comparators outputs.

If envelope detector  $Z < \frac{A}{2}$  then  $C_1=C_2=C_3=0$  and  $\phi_0(t)$  is detected. If  $\frac{3A}{2} > Z > \frac{A}{2}$  then  $C_1=1, C_2=C_3=0$  and  $\phi_1(t)$  is detected and so on.

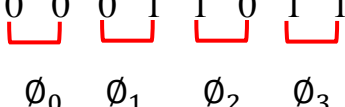
### Application of MASK:

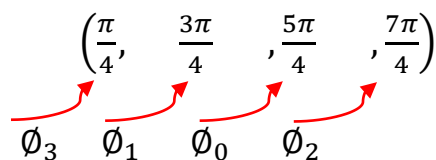
MASK has little application on telephone or space channels (sensitive to amplitude variation).

### Multilevel PSK (MPSK):

#### (a) 4- Level PSK $\equiv$ QPSK $\equiv$ Quadrature PSK:

Here  $M=4, r=2$  with constant carrier amplitude and frequency.

Data 0 0 0 1 1 0 1 1  $\phi_0(t), \phi_1(t), \phi_3(t)$  and  $\phi_2(t) \dots,$   

are assignments with four phases

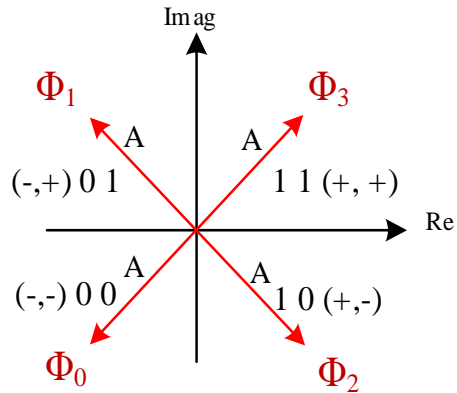


Note that the gray coding is used (symbols used at adjacent phases differ by one bit).

Hence:

$$QPSK \text{ o/p} = \pm A \cos \omega_c t \pm A \sin \omega_c t$$

i.e QPSK is the sum of two carriers in the phase Quadrature, i.e:



$$\left. \begin{aligned} \phi_3(t) &= A \cos \omega_c t + A \sin \omega_c t \\ \phi_1(t) &= -A \cos \omega_c t + A \sin \omega_c t \\ \phi_0(t) &= -A \cos \omega_c t - A \sin \omega_c t \\ \phi_2(t) &= A \cos \omega_c t - A \sin \omega_c t \end{aligned} \right\}$$

... (6-35)

$$R_s = \frac{R_b}{2}$$

$$T_s = 2T_b$$

... (6-36)

