

Lecture 3

Variable Separation Method

The method of separation of variables combined with the principle of superposition is widely used to solve initial boundary value problems involving Linear partial differential equations .

Usually , the dependent variable $U(x, y)$ is expressed in the separable form

$$U(x, y) = X(x) Y(y)$$

Where X and Y are functions of x and y .

In many cases , the partial differential equation reduces to two ordinary differential equations for X and Y .

The method is widely used in finding solutions of a large class of initial boundary value problems .

This method of solution is also as the method Eigen function expansion .

$$U(x, y) = X(x) Y(y)$$

$d U(x, y)/ dx - d U(x, y)/dy = 0$ by substitution where X is function of x and Y is function of y .

$$dX(x) dY(y)/ dx - dX(x) dY(y)/dy = 0 \quad \text{by divided } X(x) Y(y)$$

$$1/X(x) dX(x)/ dx - 1/ Y(y) dY(y)/dy = 0$$

$$1/X(x) dX(x)/ dx = C$$

$$dX(x)/X(x) = C dx$$

$$\ln X(x) = C X + G$$

$$X = e^{CX+G} \dots\dots X = Ae^{CX}$$

$$1/ Y(y) dY(y)/dy = C$$

$$dY/Y(y) = C dy$$

$$\ln Y = Cy + R$$

$$Y = e^{CY+R} \dots\dots Y = Be^{CY}$$

A, B are constantAB= D

$$U(x, y) = X(x) Y(y)$$

$$U(x, y) = Ae^{CX} \cdot Be^{CY} = AB e^{C(X+Y)}$$

$$U(x, y) = D e^{C(X+Y)}$$

Classical Mechanics:

The classical mechanics describes the behavior of objects in terms of two equations .

One equation expresses the fact that the total energy is constant in the absence of external forces .

The other equation expresses the response of particles to the forces on them .

$$\text{Velocity} = X_2 - X_1 / t_2 - t_1 = dx / dt = X'$$

$$\text{Acceleration} = X'_2 - X'_1 / t_2 - t_1 = d^2X / dt^2 = dX' / dt = X''$$

$$F(x) = m X''$$

F= force , m= mass , X'' = acceleration

$$F(q) = m q..$$