

Intel Processors Generations

Intel 8086

- The 8086 is a **16-bit** microprocessor chip designed by **Intel** between early **1976 and 1978**, when it was released. The Intel **8088**, released July **1979**, is a slightly modified chip with an **external 8-bit data bus**.
- The 8086 gave rise to the x86 architecture, which eventually became Intel's most successful line of processors.
- On **June 5th 2018**, Intel released a limited-edition CPU celebrating the anniversary of the Intel 8086, called the Intel **Core i7-8086K**.



Processing Unit Design

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Memory

Program, data and stack memories occupy the same memory space. The total addressable memory size is 1MB KB. As the most of the processor instructions use 16-bit pointers the processor can effectively address only 64 KB of memory. To access memory outside of 64 KB the CPU uses special segment registers to specify where the code, stack and data 64 KB segments are positioned within 1 MB of memory (see the "Registers" section below).

16-bit pointers and data are stored as:

address: low-order byte

address+1: high-order byte

32-bit addresses are stored in "segment: offset" format as:

address: low-order byte of segment

address+1: high-order byte of segment

address+2: low-order byte of offset

address+3: high-order byte of offset

Physical memory address pointed by segment: offset pair is calculated as:

address = (<segment> * 16) + <offset>

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- **Program memory :**

program can be located anywhere in memory.

- **Data memory :**

the 8086 processor can access data in any one out of 4 available segments, which limits the size of accessible memory to 256 KB (if all four segments point to different 64 KB blocks). Accessing data from the **Data**, **Code**, **Stack** or **Extra** segments can be usually done by prefixing instructions with the DS, CS, SS or ES (some registers and instructions by default may use the ES or SS segments instead of DS segment).

- **Stack memory:**

can be placed anywhere in memory

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Interrupts

The processor has the following interrupts:

- INTR is a maskable hardware interrupt.
- NMI is a non-maskable interrupt.

Software interrupts can be caused by:

- INT instruction - breakpoint interrupt. This is a type 3 interrupt.
- INT <interrupt number> instruction - any one interrupt from available 256 interrupts.
- INTO instruction - interrupt on overflow

I/O ports

65536 8-bit I/O ports. These ports can be also addressed as 32768 16-bit I/O ports.

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Registers

Most of the registers contain **data/instruction offsets** within 64 KB memory segment. There are four different **64 KB segments** for instructions, stack, data and extra data. To specify where in **1 MB** of processor memory these 4 segments are located the 8086 microprocessor uses four segment registers:

- **Code segment (CS)** is a **16-bit register** containing **address of 64 KB** segment with processor instructions. The processor uses CS segment for all accesses to instructions referenced by instruction pointer (IP) register.

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- **Stack segment (SS)** is a **16-bit register** containing **address of 64KB** segment with program stack.
- **Data segment (DS)** is a **16-bit register** containing **address of 64KB** segment with program data. By default, the processor assumes that all data referenced by general registers (AX, BX, CX, DX) and index register (SI, DI) is located in the data segment. DS register can be changed directly using POP and LDS instructions.
- **Extra segment (ES)** is a **16-bit register** containing **address of 64KB** segment, usually with program data

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All **general registers** of the 8086 microprocessor can be used for **arithmetic and logic operations**. The general registers are:

- **Accumulator** register consists of **2 8-bit registers** AL and AH, which can be combined together and used as a **16-bit register AX**. AL in this case contains the **low-order byte** of the word, and AH contains the **high order** byte. Accumulator can be used for **I/O operations and string manipulation**.
- **Base** register consists of **2 8-bit registers** BL and BH, which can be combined together and used as a **16-bit register BX**. BL in this case contains the **low-order byte** of the word, and BH contains the **high-order byte**. BX register usually contains a **data pointer** used for **based, based indexed or register indirect addressing**.

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- **Count register** consists of 2 8-bit registers CL and CH, which can be combined together and used as a 16-bit register CX. When combined, CL register contains the low-order byte of the word, and CH contains the high-order byte. Count register can be used as a counter in string manipulation and shift/rotate instructions.
- **Data register** consists of 2 8-bit registers DL and DH, which can be combined together and used as a 16-bit register DX. When combined, DL register contains the low-order byte of the word, and DH contains the high-order byte. Data register can be used as a port number in I/O operations

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The following registers are **both general** and **index registers**:

- **Stack Pointer (SP)** is a **16-bit** register pointing to program stack.
- **Base Pointer (BP)** is a **16-bit** register pointing to data in stack segment. **BP** register is usually **used** for **based, based indexed** or **register indirect addressing**.
- **Source Index (SI)** is a **16-bit** register. **SI** is **used** for **indexed, based indexed** and **register indirect addressing**, as well as a source data address in string manipulation instructions.
- **Destination Index (DI)** is a **16-bit** register. **DI** is **used** for **indexed, based indexed** and **register indirect addressing**, as well as a destination data address in string manipulation instructions.

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Other registers:

Instruction Pointer (IP) is a 16-bit register.

Flags is a 16-bit register containing 9 1-bit flags:

1. Overflow Flag (OF)
2. Direction Flag (DF)
3. Interrupt-enable Flag (IF)
4. Single-step Flag (TF)
5. Sign Flag (SF)
6. Zero Flag (ZF)
7. Auxiliary carry Flag (AF)
8. Parity Flag (PF)
9. Carry Flag (CF)

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Instruction Set

Instruction set of Intel 8086 processor consists of the following instructions:

1. Data moving instructions.
2. Arithmetic - add, subtract, increment, decrement, convert byte/word and compare.
3. Logic - AND, OR, exclusive OR, shift/rotate and test.
4. String manipulation - load, store, move, compare and scan for byte/word.
5. Control transfer - conditional, unconditional, call subroutine and return from subroutine.
6. Input / Output instructions.
7. Other - setting/clearing flag bits, stack operations, software interrupts, etc.

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Addressing modes

1. **Implied** - the data value/data address is implicitly associated with the instruction.
2. **Register** - references the data in a register or in a register pair.
3. **Immediate** - the data is provided in the instruction.
4. **Direct** - the instruction operand specifies the memory address where data is located.
5. **Register indirect** - instruction specifies a register containing an address, where data is located. This addressing mode works with SI, DI, BX and BP registers.

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6. **Based** - 8-bit or 16-bit instruction operand is added to the contents of a base register (BX or BP), the resulting value is a pointer to location where data resides.
7. **Indexed** - 8-bit or 16-bit instruction operand is added to the contents of an index register (SI or DI), the resulting value is a pointer to location where data resides.
8. **Based Indexed** - the contents of a base register (BX or BP) is added to the contents of an index register (SI or DI), the resulting value is a pointer to location where data resides.
9. **Based Indexed with displacement** - 8-bit or 16-bit instruction operand is added to the contents of a base register (BX or BP) and index register (SI or DI), the resulting value is a pointer to location where data resides.

Processing Unit Design

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Intel 8086 registers

1₉ 1₈ 1₇ 1₆ 1₅ 1₄ 1₃ 1₂ 1₁ 1₀ 0₉ 0₈ 0₇ 0₆ 0₅ 0₄ 0₃ 0₂ 0₁ 0₀ (bit position)

Main registers

	AH	AL	AX (primary accumulator)
	BH	BL	BX (base, accumulator)
	CH	CL	CX (counter, accumulator)
	DH	DL	DX (accumulator, extended acc.)

Index registers

0 0 0 0	SI	Source Index
0 0 0 0	DI	Destination Index
0 0 0 0	BP	Base Pointer
0 0 0 0	SP	Stack Pointer

Program counter

0 0 0 0	IP	Instruction Pointer
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Segment registers

CS	0 0 0 0	Code Segment
DS	0 0 0 0	Data Segment
ES	0 0 0 0	Extra Segment
SS	0 0 0 0	Stack Segment

Status register

- - - - O D I T S Z - A - P - C	Flags
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The **Intel 8088** ("eighty-eighty-eight") microprocessor is a variant of the **Intel 8086**. Introduced on **July 1979**, the 8088 had an **eight-bit external data bus** instead of the **16-bit bus of the 8086**. The **16-bit registers and the one megabyte address** range were unchanged, however. In fact, according to the Intel documentation, the **8086 and 8088 have the same execution unit (EU)** only the **bus interface unit (BIU) is different**. The original IBM PC was based on the 8088.

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CPU Basics

A typical CPU has three major components:

(1) Register set

(2) Arithmetic logic unit (ALU)

(3) Control unit (CU)

- **The register** set differs from one computer architecture to another. It is usually a combination of general-purpose and special purpose registers.
- **General-purpose registers** are used for *any purpose*, hence the name general purpose.
- **Special-purpose registers** have *specific functions* within the CPU. For example, the *program counter (PC)* is a special-purpose register that is used to **hold the address of the instruction to be executed next**. Another example of special-purpose registers is the *instruction register (IR)*, which is used to **hold the instruction that is currently executed**.

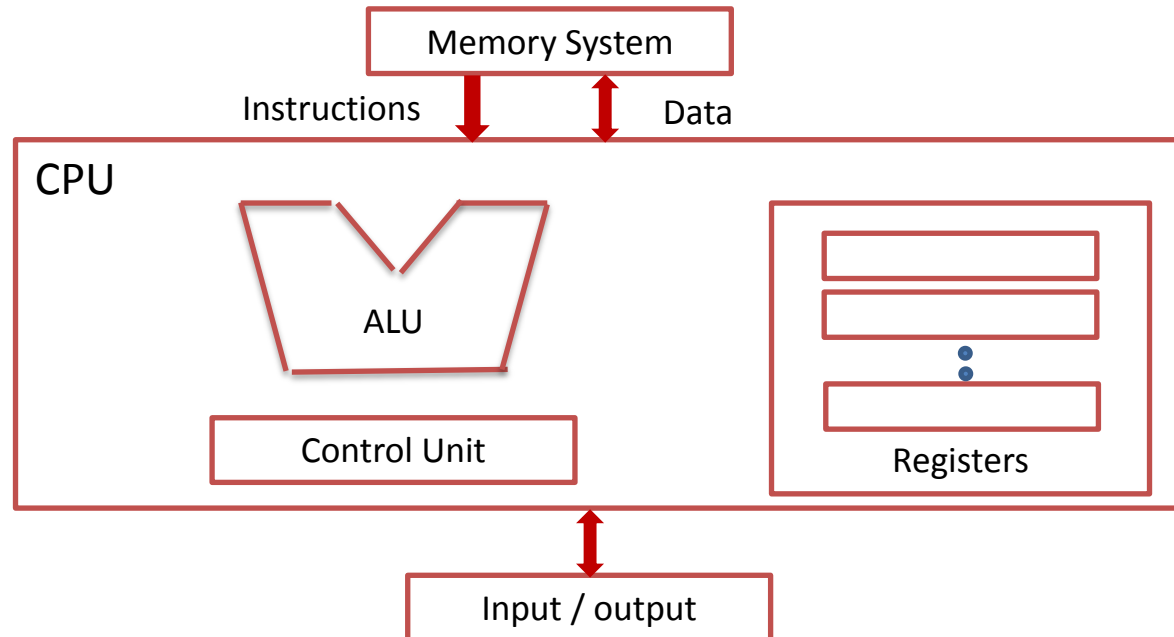
Processing Unit Design

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- The **ALU** provides the circuitry needed to **perform the arithmetic, logical and shift operations demanded** of the **instruction set**.
- The **control unit** is the entity responsible for **fetching the instruction** to be **executed** from the **main memory** and **decoding** and then **executing** it.

Figure below shows the **main components of the CPU** and **its interactions** with the **memory system** and the **input/output** devices.



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The **CPU fetches instructions** from **memory**, **reads** and **writes** data from and to memory, and **transfers** data from and to **input/output devices**. A typical and simple execution cycle can be summarized as follows:

1. The **next instruction** to be executed, whose address is **obtained** from the **PC**, is fetched from the **memory** and stored in the **IR**.
2. The instruction is **decoded**.
3. **Operands** are fetched from the **memory** and stored in **CPU** registers, if needed.
4. The instruction is **executed**.
5. **Results** are **transferred** from **CPU registers** to the **memory**, if needed.

The **actions** of the **CPU during an execution cycle** are defined by micro-orders issued by the control unit. These micro-orders are individual control signals **sent over dedicated control lines**.

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For example

- Let us assume that we want to **execute an instruction** that *moves* the contents of **register X** to **register Y**.
- Let us also assume that **both registers** are *connected* to the **data bus**, D.
- The control unit will issue a **control signal** to tell **register X** to *place* its contents on the **data bus D**. After some delay,
- another **control signal** will be *sent* to tell **register Y** to *read* from data bus D. The activation of the **control signals** is determined using either hardwired control or microprogramming.

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Register Set

Registers are essentially **extremely fast memory locations** within the **CPU** that are **used** to **create and store** the results of **CPU** operations and other **calculations**. Different computers have *different register sets*.

❖ Memory Access Registers

Two registers are essential in memory **write** and **read** operations: the *memory data register (MDR)* and *memory address register (MAR)*.

In order to **perform** a **write operation** into a **specified memory location**, the **MDR and MAR** are used as follows:

1. The **word** to be **stored** into the **memory location** is **first loaded** by the **CPU** into **MDR**.
2. The **address** of the **location** into which the **word** is to be **stored** is **loaded** by the **CPU** into a **MAR**.
3. A **write signal** is **issued** by the **CPU**.

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To perform a **memory read operation**, the **MDR** and **MAR** are used as follows:

1. The **address** of the **location** from which the **word** is to be **read** is **loaded** into the **MAR**.
2. A **read signal** is **issued** by the **CPU**.
3. The **required word** will be **loaded** by the **memory** into the **MDR** ready for **use** by the **CPU**.

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❖ Instruction Fetching Registers

Two main registers are involved in **fetching an instruction** for **execution**: the *program counter (PC)* and the *instruction register (IR)*.

- The *PC* is the register that **contains** the **address of the next instruction** to be **fetched**.
- The **fetched instruction** is **loaded** in the *IR* for **execution**.
- After a **successful instruction fetch**, the *PC* is **updated** to point to the **next instruction** to be **executed**.
- In the case of a **branch operation**, the *PC* is **updated** to point to the **branch target instruction** after the branch is **resolved**, that is, the target address is **known**.

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❖ **Condition Registers**

Condition registers, or flags, are **used** to maintain status information.

Some architectures **contain** a special program status word (*PSW*) register.

The *PSW* contains **bits** that are **set** by the *CPU* to **indicate** the **current status** of an **executing program**. These **indicators** are typically for **arithmetic operations, interrupts, memory protection information, or processor status**.

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❖ Special-Purpose Address Registers

- **Index Register:** The index register **holds** an **address displacement**. Index addressing is **indicated** in the instruction by **including** the **name of the index register** in parentheses and using the **symbol X** to **indicate** the constant to be added.
- **Segment Pointers:** the **address** issued by the **processor** should **consist** of a **segment number (base)** and a **displacement (or an offset)** within the segment. A segment register **holds** the **address of the base** of the segment.
- **Stack Pointer:** Two specific operations can be **performed** on a **stack**. These are the **Push** and the **Pop** operations. A specific register, called the **stack pointer (SP)**, is **used** to **indicate** the **stack location** that can be addressed. In the **stack push** operation, the **SP value** is used to **indicate** the **location** (called the top of the stack). After storing (pushing) this value, the SP is incremented.

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➤ The Bus

The CPU communicates with the other components via a *bus*.

A bus is a set of wires that acts as a shared but common data path to connect multiple subsystems within the system. It consists of multiple lines, allowing the parallel movement of bits.

Internal to the CPU, data move from one register to another and between ALU and registers.

Internal data movements are performed via **local buses**, which may carry data, instructions, and addresses.

Externally, data move from registers to memory and I/O devices, often by means of a **system bus**.

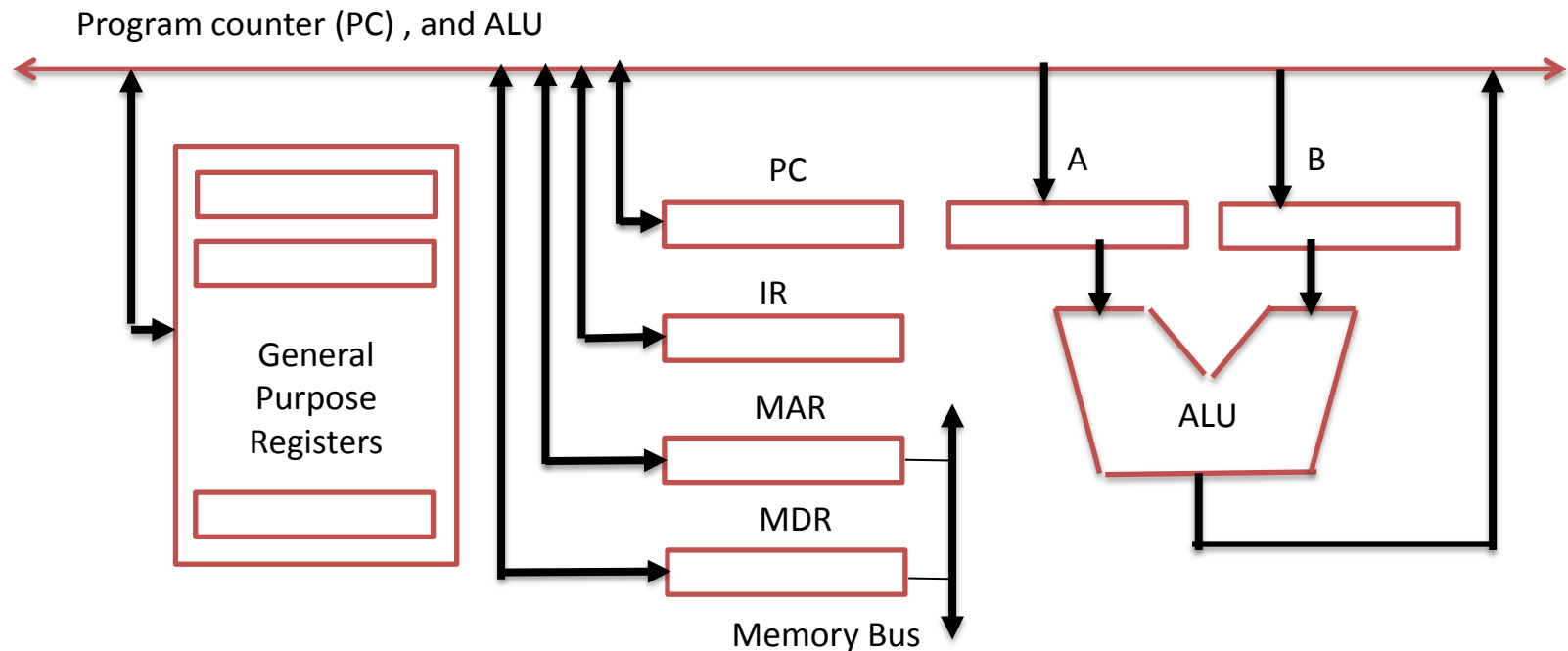
Internal data movement among registers and between the ALU and registers may be carried out using different organizations including one-bus, two-bus, or three-bus organizations.

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❖ One-Bus Organization

Using one bus, the CPU registers and the ALU use a single bus to move outgoing and incoming data. Since a bus can handle only a single data movement within one clock cycle, two-operand operations will need two cycles to fetch the operands for the ALU. Additional registers may also be needed to buffer data for the ALU.

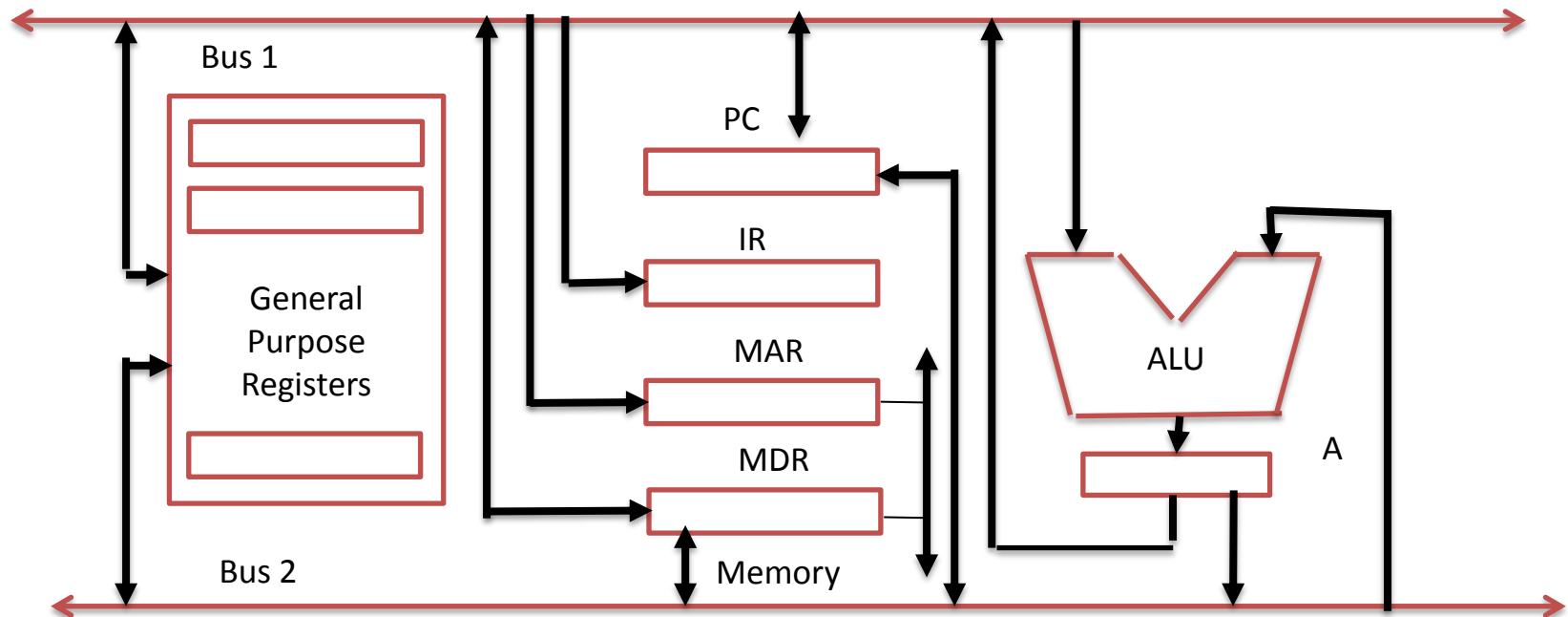


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❖ Two-Bus Organization

Using two buses is a faster solution than the one-bus organization. In this case, general-purpose registers are connected to both buses. Data can be transferred from two different registers to the input point of the ALU at the same time. Therefore, a two-operand operation can fetch both operands in the same clock cycle. An additional buffer register may be needed to hold the output of the ALU when the two buses are busy carrying the two operands.



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❖ Three-Bus Organization

In a three-bus organization, two buses may be used as source buses while the third is used as destination. The source buses move data out of registers (out-bus), and the destination bus may move data into a register (in-bus). Each of the two out-buses is connected to an ALU input point. The output of the ALU is connected directly to the in-bus. As can be expected, the more buses we have, the more data we can move within a single clock cycle. However, increasing the number of buses will also increase the complexity of the hardware.

