<u>Part (1)</u>

Classification of computer architecture

Flynn's taxonomy

Classification of computer systems

- Michael Flynn 1966
 - Classification based on the presence of single or multiple streams of instructions and data
- Instruction stream: a sequence instructions executed by a processor
- Data stream: a sequence of data required by an instruction stream

Flynn's taxonomy

Single data streamSISD – Single Instruction Single DataMISD – Multiple Instruction Single DataMultiple data streamsSIMD – Single Instruction Multiple DataMIMD – Multiple Instruction Multiple Data		Single instruction stream	Multiple instruction streams
Multiple data streamsSIMD - Single Instruction Multiple DataMIMD - Multiple Instruction Multiple Data	Single data stream	SISD – Single Instruction Single Data	MISD – Multiple Instruction Single Data
	Multiple data streams	SIMD – Single Instruction Multiple Data	MIMD – Multiple Instruction Multiple Data





Flynn's taxonomy

- > MISD Multiple instruction flows and single data flow
 - two view:
 - there is no such a computer
 - pipeline architectures may be considered in this class
 - instruction level parallelism
 - superscalar architectures sequential from outside, parallel inside
- > MIMD Multiple instruction flows and multiple data flows
 - true parallel architectures
 - multi-cores
 - multiprocessor systems: parallel and distributed systems

Von Neumann Machines:

• The von Neumann architecture refers to Hungarian-American mathematician John von Neumann, Von Neumann became a consultant to the ENIAC (Electronic Numerical Integrator and Computer), which upon its completion in 1945 became the world's first general purpose electronic computer.



* The principal feature of a von Neumann computer is that the program and any data are both stored together,

A von Neumann computer has five parts:

- * arithmetic-logic unit
- * control unit
- * memory
- * some form of input/output
- * A bus that provides a data path between these parts.

Such a computer operates by performing the following sequence of steps:

- **1.** Fetch the next instruction from memory at the address in the program counter.
- **2.** Add the length of the instruction to the program counter.
- **3.** Decode the instruction using the control unit. The instruction may change the address in the program counter, permitting repetitive operations. The instruction may also change the program counter only if some arithmetic condition is true.
- **4.** Go back to step 1.

Von Neumann computers have some *drawbacks:*

- **1.** They carry out instructions one after another, in a single linear sequence.
- **2.** They spend a lot of time moving data to and from the memory.

This slows the computer leading to a problem called the von Neumann bottleneck. One way to solve the **von Neumann bottleneck** is:

- **1.** Build the computer so it performs operations in parallel (so-called parallel processing).
- **2.** Another common trick is to separate the bus into two or more busses, one for instructions, another for data.

Example of Non Von Neumann Architecture

*One example is the <u>MIMD</u> architecture which is: Multiple instruction/Multiple data

*Other examples are Analog Computers, Optical Computers, Quantum Computers, Cell Processors, DNA, Neural Nets (in Silicon).

*Most Non Von Neumann models <u>distributes the computation</u> amongst processing units - for example FPGA or neural networks.

*They can be thought of as a class of computer programs ideally suited for <u>parallel computation</u>.